

[IT ] Robot Ontology

Study Group

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7 IEEE Standards Board IEEE Robotics and Automation Society Industrial Activity Board(IAB, : ) ( : Erwin Prassler )

IEEE IAB Study Group(SG) Working Group(WG) IEEE Proposal Authorization Request(PAR) IEEE Standards Board ,

IEEE IAB 2007 10 29 11 3

IROS 2007 Robot Ontology(Robot Ontology for Mobile Manipulation and Service Robotics) Study Group

IEEE Robot

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(rapid prototyping) 가

H/W S/W , ,

가가

H/W S/W 가 가 . IEEE RAS IAB

IEEE

robot ontology .

Robot Ontology Study Group

1. Robot Ontology ?

Ontology , ,

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가 . Ontology  
 가 (semantic) . Ontology  
 가 . Robot Ontology

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2007 IAB IEEE IROS 2007 가  
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(Human-System Interaction)	
(Logistics)	
(Operating Environment)	/
(System)	, 가 가 (capability). ( )

(Chassis)	가 (capability)
(Communications)	,
(Mobility)	
(Payload)	가
(Power)	
(Sensing)	(sense)
(Safety)	(vicinity)

IEEE RAS IAB

- Robot Ontology 가
  - ontology standard 가
  - ontology
  - ontology standard
- feedback

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가

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