

[IT] Robot Ontology

Study Group

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7 IEEE Standards Board IEEE Robotics and Automation Society Industrial Activity Board(IAB, :) (: Erwin Prassler)
 IEEE IAB Study Group(SG) Working Group(WG) IEEE Proposal Authorization Request(PAR) IEEE Standards Board ,
 IEEE IAB 2007 10 29 11 3 IROS 2007 Robot Ontology(Robot Ontology for Mobile Manipulation and Service Robotics) Study Group

IEEE Robot

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가 (rapid prototyping) 가

H/W S/W , ,
 H/W S/W 가 가 IEEE RAS IAB
 IEEE
 robot ontology .

Robot Ontology Study Group

1. Robot Ontology ?

Ontology , ,
 . Ontology

가 . Ontology
 가 (semantic) . Ontology
 가 . Robot Ontology

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2.

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2007 IAB IEEE IROS 2007 가
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(Human - System Interaction)	
(Logistics)	
(Operating Environment)	/
(System)	, 가 가 (capability). ()

(Chassis)	가 (capability)
(Communications)	,
(Mobility)	
(Payload)	가
(Power)	
(Sensing)	(sense)
(Safety)	(vicinity)

IEEE RAS IAB

- Robot Ontology 가
 - ontology standard 가
 - ontology
 - ontology standard
- feedback

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가

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